GLAMBOT®

QUICK START GUIDE

Instructions to assemble the modular components + capture cinematic videos.

Rev. 10 | effective: 02/20/26

PART 1: ASSEMBLY INSTRUCTIONS

WARNING: A collision with Glambot® may cause physical damage to property, person, or the robotic arm. Ensure proper clearance of the robot at all times. All persons and objects must remain outside the work envelope. By operating Glambot® you are assuming the associated risks and liabilities.

BEFORE YOU START

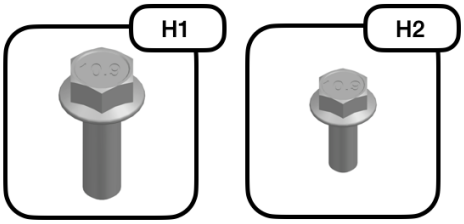
Please review all the requirements, understand the safety precautions, and prepare the appropriate tools prior to beginning the assembly and initialization of the robotic arm.

ASSEMBLY REQUIREMENTS

SPACE	PERSONNEL	SURFACE	TIME
10ft x 10ft footprint 9ft high	team lift	solid + stable ground	estimated time 30 min

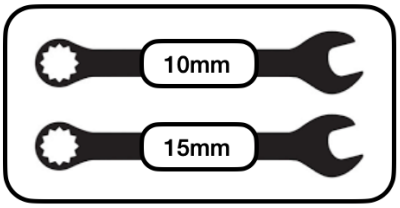
HARDWARE [INCLUDED]

(8) H1 - M10 x 1.5 x 30L flanged hex head screw
(4) H2 - M6 x 1.0 x 16L flanged hex head screw



TOOLS [INCLUDED]

15mm wrench
10mm wrench



RESOURCES

Get a step-by-step video tutorial on setting up your Glambot®

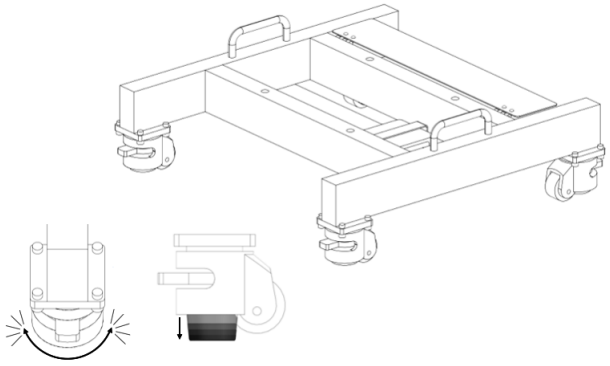
If you have any questions during your deployment, please call +1 (855) GLAMBOT

For more information and videos visit: www.getglambot.com/glambot-resources

SCAN ME

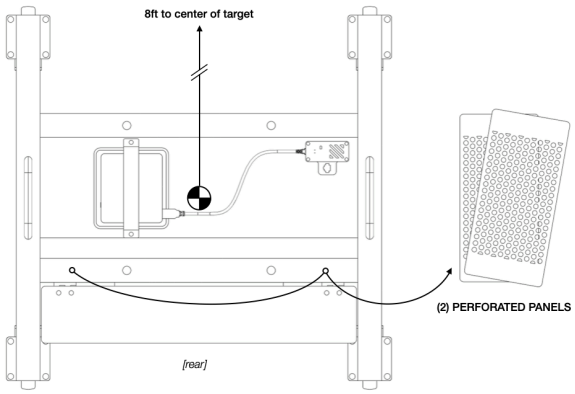
ROBOT ASSEMBLY

1. **BASE INSTALLATION:** Place the BASE on the floor in the desired location with the power strip facing back. Level the BASE using the ratchet adjustment integrated into each of the (4) casters.

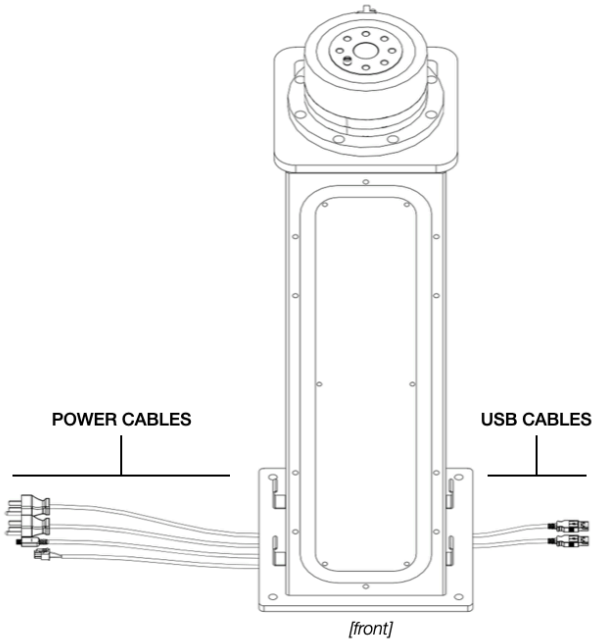


PRO TIP: use the integrated ratchet lever to extend the rubber foot to the ground.

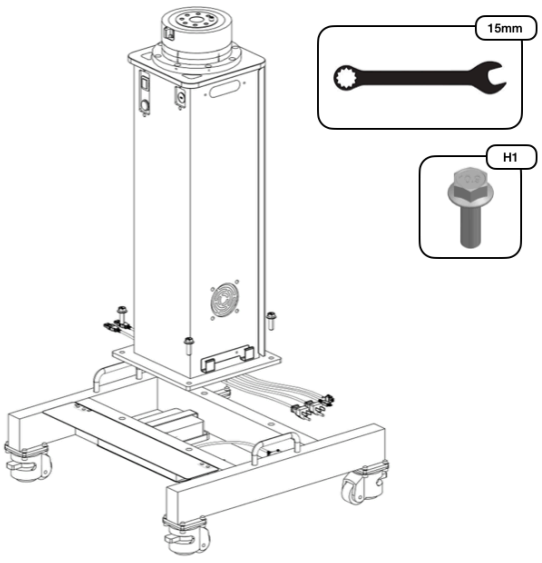
2. **BASE PREPARATION:** Align and locate the center of the base 8ft from the desired target location. Remove the (2) magnetic PERFORATED PANELS to allow access to the electronics and wiring.



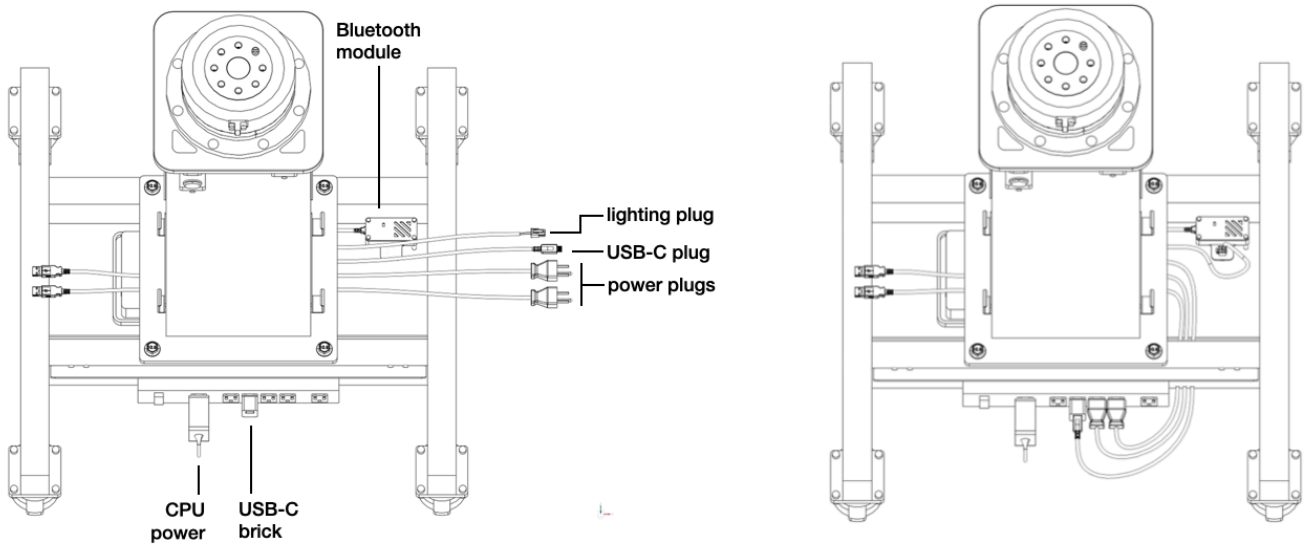
3. **PEDESTAL PREPARATION:** Facing the front of the tower ensure the POWER CABLES are laid to the left and the USB CABLES are laid to the right.



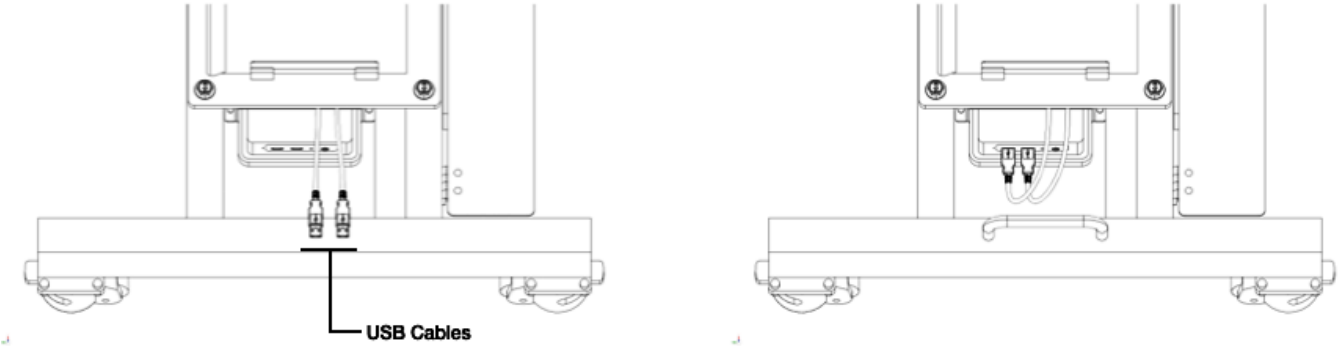
4. **PEDESTAL INSTALLATION:** Place the PEDESTAL centered on the BASE aligning the mounting holes checking that no wires are pinched. Using the 15mm wrench, attach the (4) M10 flanged hex head bolts - labeled H1. Tighten securely.



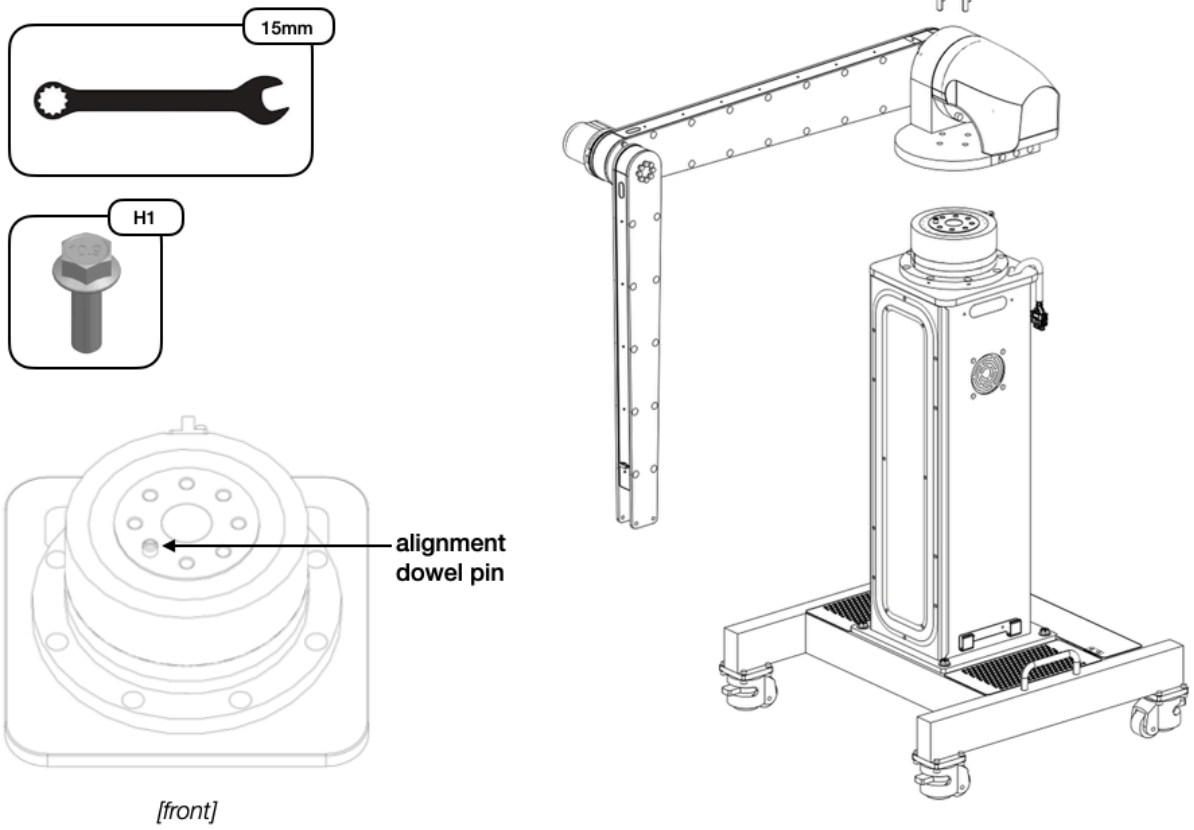
5. **PEDESTAL POWER WIRING:** Route the (2) power plugs + (1) USB-C cable under the frame and plug into the power strip at the rear of the BASE. Follow the CPU power for a routing reference to the power strip. The USB-C cable will land at the power brick that remains on the power strip. Route the (1) data plug directly to the BLE module.



6. **PEDESTAL USB WIRING:** Plug the (2) USB-A cables into the mini-PC. Re-install the (2) magnetic PERFORATED PANELS.

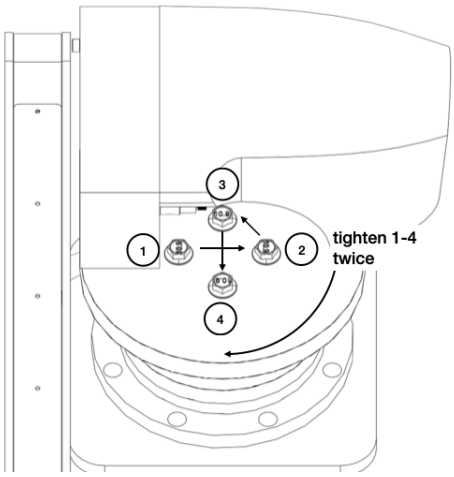


7. **SHOULDER INSTALLATION:** Extend the elbow joint out from the stowed 160° to 90°. With the ARM directed straight ahead to the front, align the dowel pin, and set on the PEDESTAL. Attach using the (4) M10 flanged hex head bolts - labeled H1. Tighten securely in a cross pattern.



Note: recommend having (1) bolt ready to install and hold the arm once located

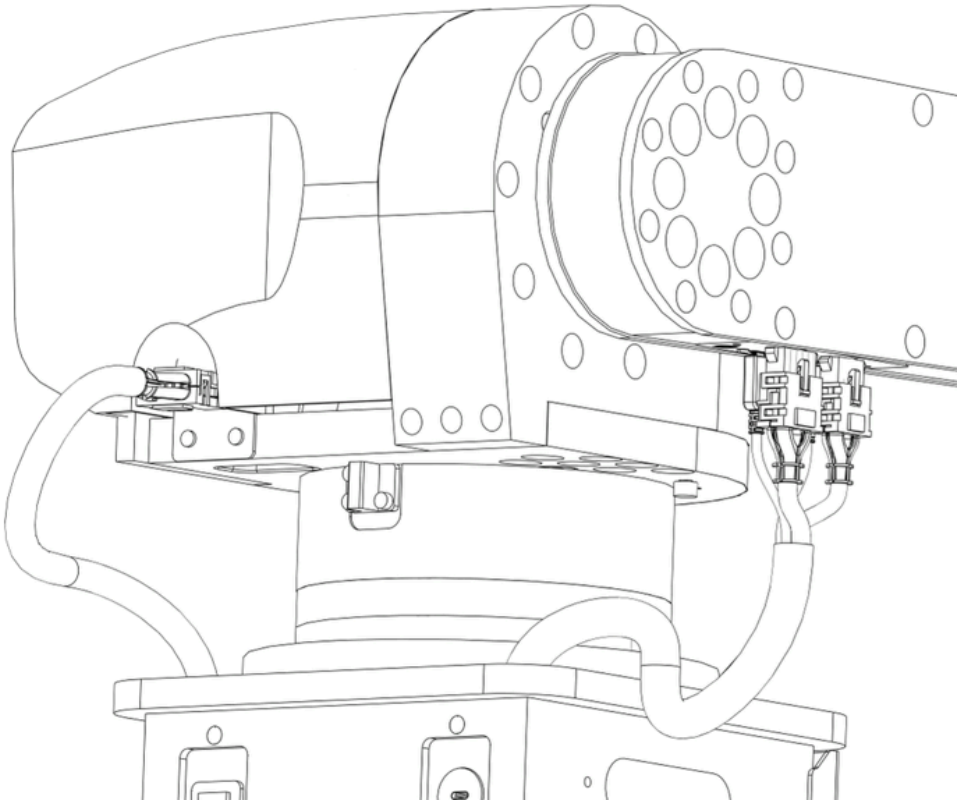
Note: to fully tighten this connection, perform the cross pattern tightening sequence at least twice.



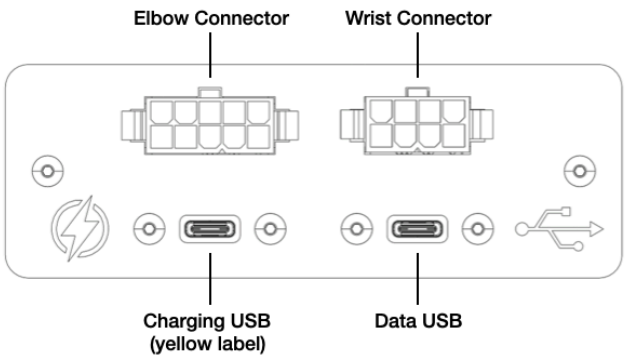
8. **SHOULDER WIRING:** Looking from the rear, begin with the right-side harness. Plug in the (4) connectors into the panel on the bottom side of the ARM:

    - 10-pin elbow connector
    - 8-pin wrist connector
    - USB-C cable [power] *signified by a yellow collar on the cable*
    - USB-C cable [data]

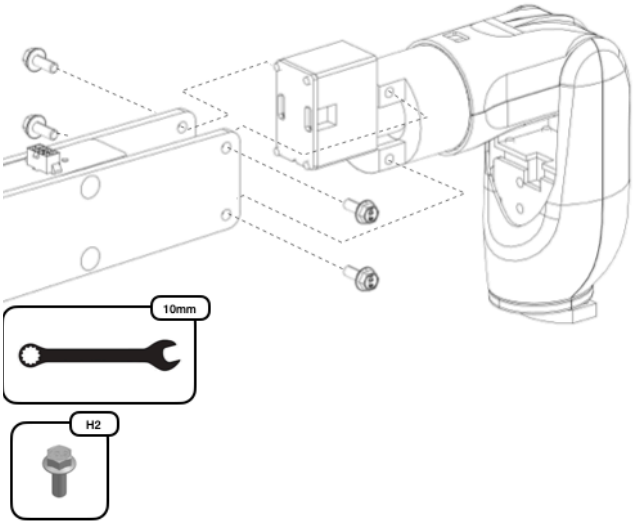
    Then, attach the left-side harness. Plug in the (1) connector of the lift motor harness to the integrated plug:



ARM Detail

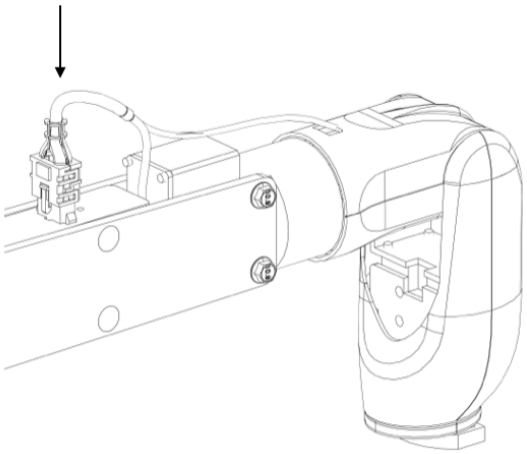


9. **WRIST INSTALLATION:** Extend ARM2 to the horizontal position. Orient the wrist assembly such that the nesting motor protrudes up out the top of the arm. Slide the wrist assembly between the plates at the end of the ARM assembly. Using the 10mm wrench, attach the (4) M6 flanged hex head bolts - labeled H2. Tighten securely.



Note: take care not to pinch (2) cables upon inserting WRIST assembly into ARM.

10. **WRIST WIRING:** Plug in the (1) free cable to the panel on the top side of the ARM. If holding the ARM, gently let the arm fall to hang vertically.

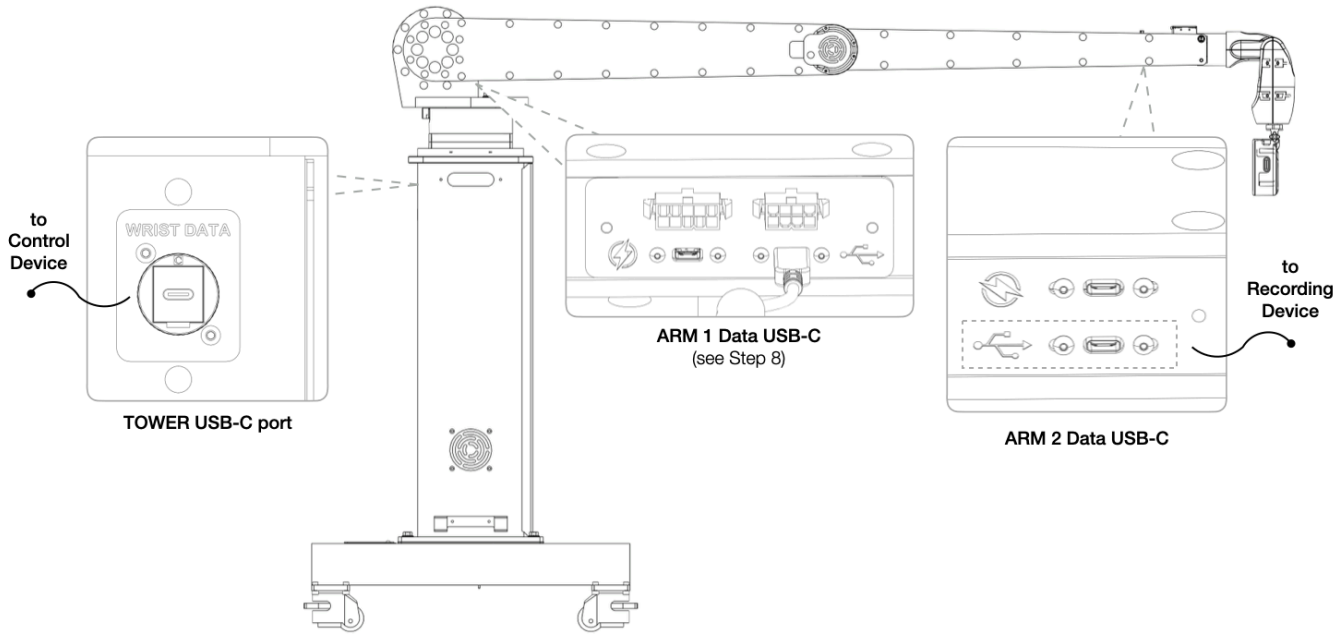


11. **END EFFECTOR INSTALLATION:** Choose your recording device and follow the instruction for that specific end effector in Appendix A. Additional hardware will be required for each mounting type.

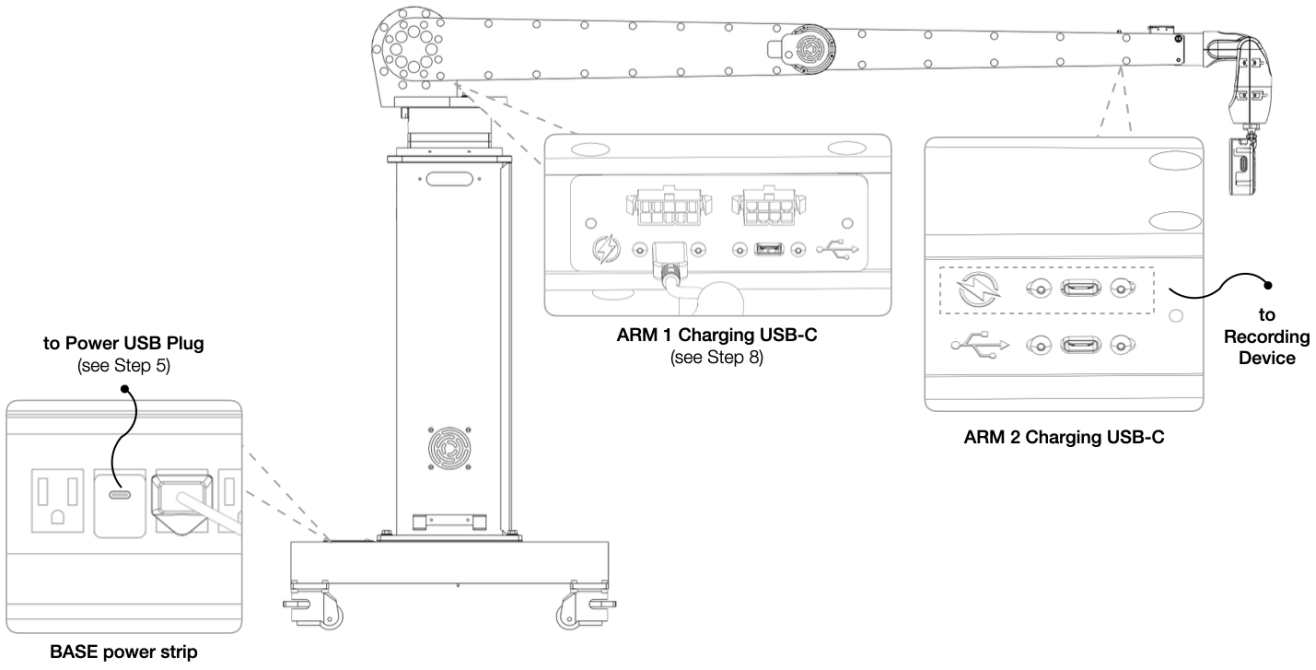
Note: Total weight of end effector assembly shall not exceed 3 lbs.

12. **ACCESSORY CONNECTIONS:** Based on your END EFFECTOR selection, determine whether you will need to connect accessory USB-C cables for charging and/or data transfer. Refer to the schematics on the next page for the Power and Data layouts through the unit:

DATA Connection:



POWER Connection



You have completed the Glambot® assembly! Proceed to the Start-up Instructions.

PART 2: START-UP INSTRUCTIONS

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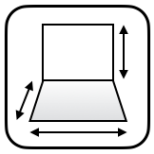
BEFORE YOU START

Please review all the requirements, understand the safety precautions, and prepare the appropriate tools prior to beginning the assembly and initialization of the robotic arm.

START-UP REQUIREMENTS

SPACE	POWER	SURFACE	TIME
			
10ft x 10ft footprint 9ft high	110-120V | 60Hz | 1500W [US NEMA 3 prong] *international requires adapter*	solid + stable ground	estimated time 10 min

RESOURCES

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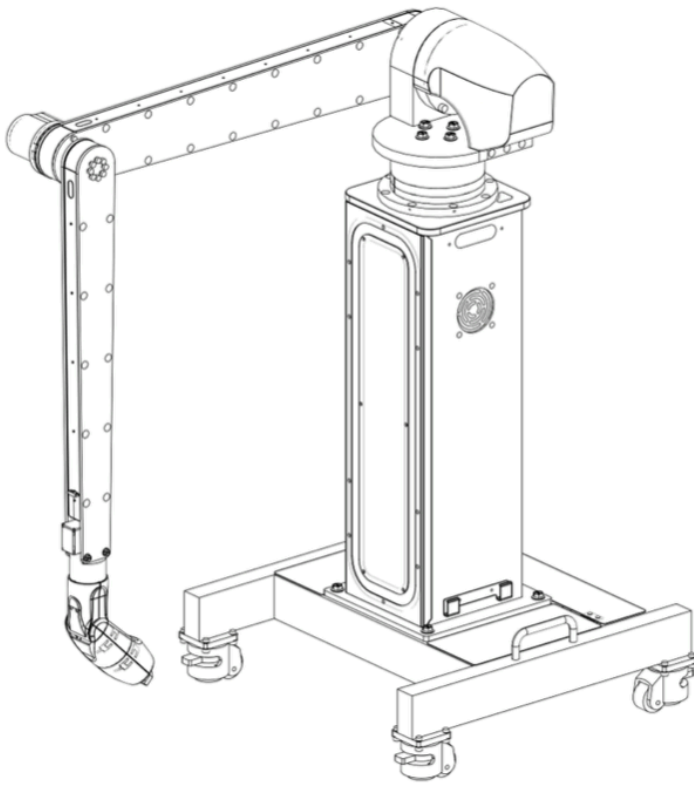
SCAN ME

DO NOT TURN ON THE GLAMBOT® PRIOR TO PERFORMING ALL THE SAFETY CHECKS

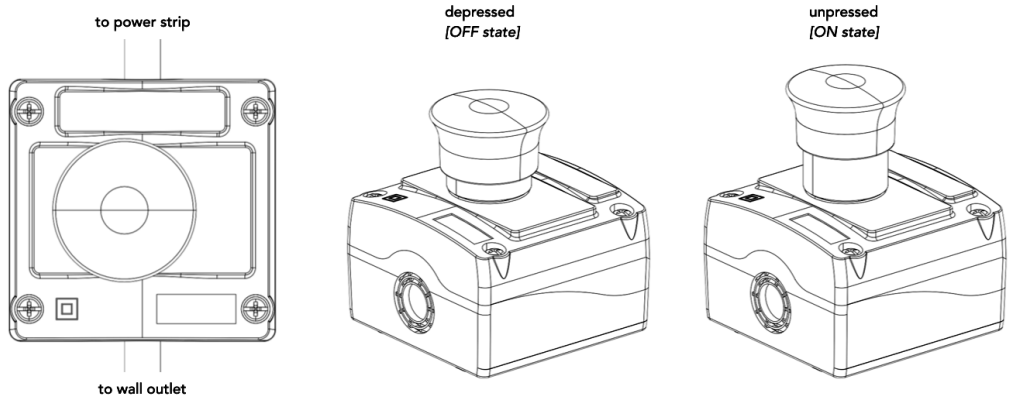
Remove any tools and equipment from the envelope of the robot before continuing.

13. **SAFETY CHECKS:** Once you have completed assembly of the Glambot® you can proceed to start-up the system for capturing videos. Before any start-up, make sure to check the following:

- ☑ The Glambot® is located securely on a sturdy surface and can remain stable during operation.
- ☑ The end effector is securely attached to the wrist and will not fall out during operation.
- ☑ All cables are intact, connected to appropriate connectors, properly secured.
- ☑ The emergency stop button is attached to the machine and is located where the operator can reach it from his/her workplace at any moment.
- ☑ All risks identified during a risk assessment of the operating environment have either been eliminated or mitigated by implementing appropriate measures.
- ☑ There are no obstacles within the envelope of the Glambot® that could prevent the are from moving freely or operating properly.



14. **POWER:** Check the status of the EMERGENCY STOP and POWER STRIP to ensure they are both in the off state. Locate a convenient receptacle and plug in the EMERGENCY STOP cable. Pull up on the emergency stop button to allow power and turn on the switch to POWER STRIP.



15. **BOOT:** The Glambot® will begin the boot sequence which lasts 30-60 seconds. No action by the attendant is required for this step. The motors will make an audible click sound upon powering up.

16. **NETWORK CONNECTION:** Following the boot sequence, the Bluetooth and Wi-Fi networks will be established. Find the following networks and pair the "Control Device" (phone, tablet, laptop) to the Glambot® Wi-Fi network and the "Recording Device" to the Glambot® Bluetooth network.

    Wi-Fi network: glambot-XXXX | pw: Glambot1!

    Bluetooth network: glambot-XXXX

    Note: refer to robot ID tag and replace XXXX with your unit number.

17. **CONTROL:** Once connected, the Glambot® will be controlled through a Glambot® Motion Control. To open the Glambot® Motion Control, navigate to the browser on the "Control Device" and enter the following web address:

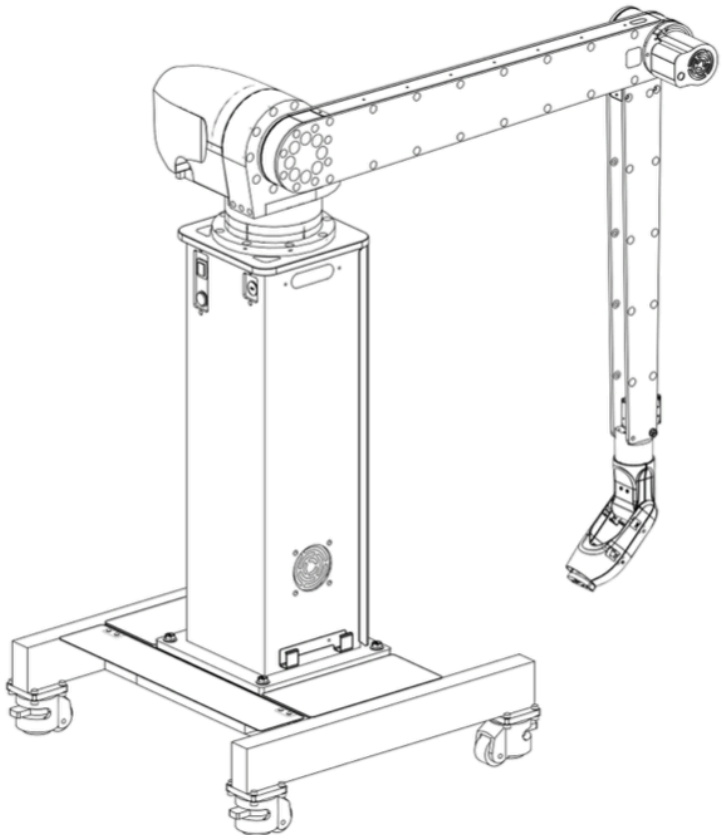
    `http://glambot-XXXX.local:8080/webapp`

    Note: refer to robot ID tag and replace XXXX with your unit number.

    Refer to Appendix B for additional information on the Glambot® Motion Control layout and operation.

18. **CALIBRATION:** Press the 'Calibrate' button on the Glambot® Motion Control to initiate the calibration sequence. First, the wrist motors will orient to their respective "zero" positions. Then, the remaining (3) motors will physically calibrate by moving through and extended range of motion in the following order: ELBOW, LIFT, PAN.

    Note: an Auto-Calibrate option is available in the 'Advanced' settings menu that will allow the Glambot to automatically begin the calibration sequence upon powering on, refer to Appendix B for additional information.



19. **EXECUTION:** Using the Glambot® Motion Control, confirm the speed selection, select the desired path, then press 'Start'. Refer to Appendix B for additional information on the Glambot® Motion Control layout and operation.

    Note: the Glambot® Motion Control will grey out all buttons except the 'Stop' button and the robot will move to the path start position, it will pause for the wait duration, the execute the path with recording a video. Upon completion, all buttons on the Glambot® Motion Control will become available again.

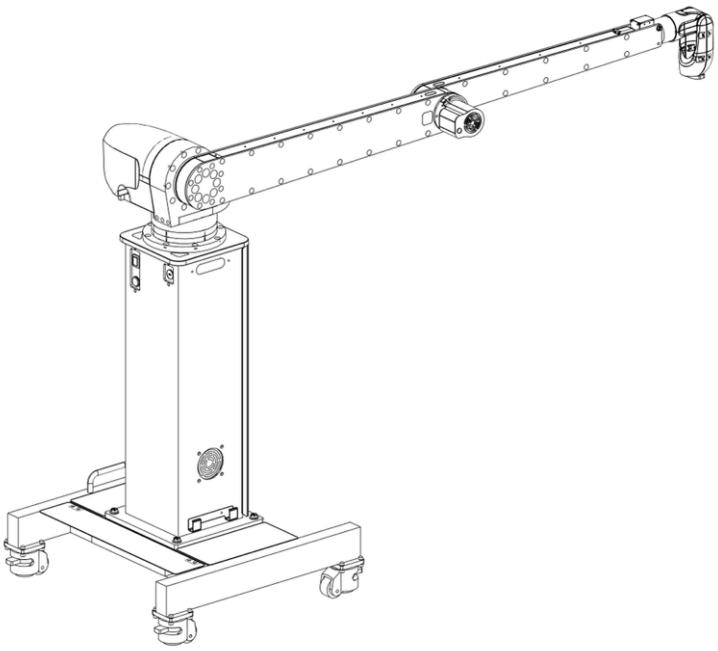
    The setup for filming varies based on the recording device and connection type. Refer to the specific setup in Appendix C.

During operation, refer to the cue light at the end of the wrist for the Glambot® status at any time.

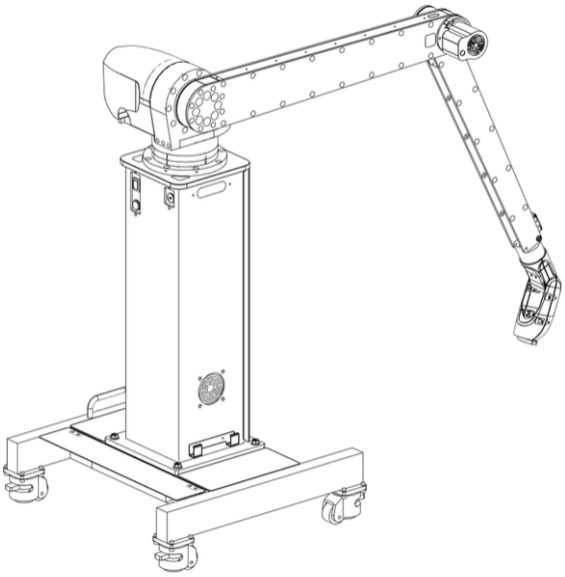
Light	Status
 Flashing Blue	Start-up and calibration
 Solid Blue	Ready - at the last commanded position and ready for the next action.
 White	Moving - to a path start position or through a command path.
 Flashing Green	Countdown - 1 second blinks to set duration.
 Flashing Red	Error - refer to Error Messages in Advanced Menu for next steps.

PART 3: DISASSEMBLY INSTRUCTIONS

20. **POWER OFF:** Using the Glambot® Motion Control, command the arm to the 'Extended' position. Depress the Emergency Stop to remove power from the arm. The motors will disengage and the ELBOW will relax.



'OFF / Extended' position



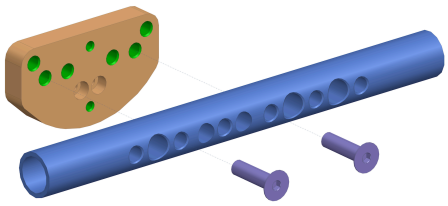
powered off status

21. **DISASSEMBLY:** The order for disassembly is opposite of assembly, starting with removing the WRIST assembly, then the ARM assembly, and finally the TOWER. When disassembling any joint first disconnect the wire connections, then remove any fasteners. Store fasteners in an orderly manner and take care not to pinch any wires during storage of the arm components.

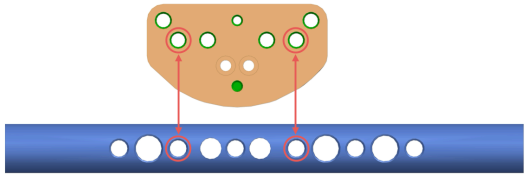
APPENDIX A: Camera Attachment

DSLR/MIRRORLESS ATTACHMENT

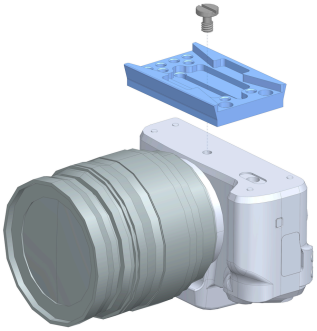
1. Install the Mounting Rod from the Universal DSLR Attachment to the Wrist coupler with (2) M5x20mm flat head screws using a 3mm hex key.



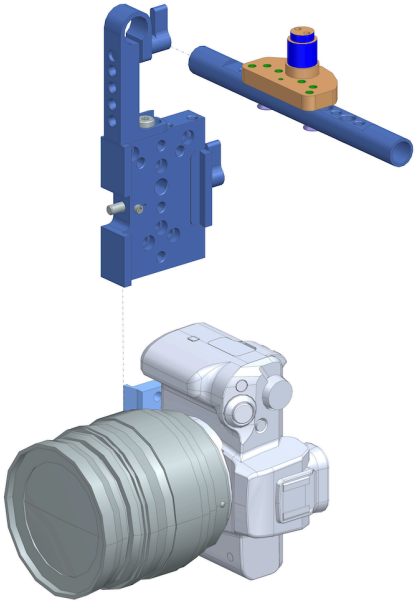
Note: align the rod with the output bracket as shown below.



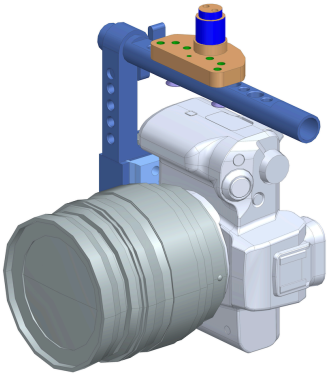
2. Prep the camera and Slider from the Universal Attachment by centering the camera on the Slider and securing with the 1/4-20 camera screw using a flat head screw driver.



3. Complete the assembly by sliding the camera onto the hanger. Press past the detent and secure with the integrated clamp. Then, slide the Hanger onto the Rod and secure with the integrated clamp.



Note: refer to the finished assembly



GO-PRO ATTACHMENT

1. Install the GoPro Adapter to the Wrist coupler with (2) M3x10mm socket cap screws using a 2.5mm hex key.

2. Slide the GoPro cage into the GoPro adapter and fasten with the (1) included M5x6mm button head screw using a 3mm hex key.

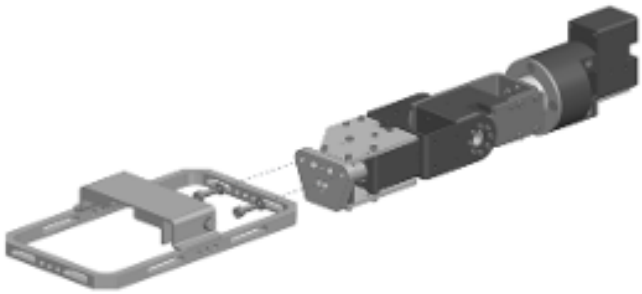
3. Slide the back cover off the cage and insert the GoPro. Then slide the Video Light onto the cage at the cold shoe location and secure with the double thumb nuts.

4. Install the (2) M3x6mm button head screws partially into the GoPro cage side mounting holes. Then, slide the plastic cover over the assembly with the slot wall behind the pre-installed screws. Tighten the screws with a 2mm hex key through the side access hole.

5. Snap the Rear Cover into the mounted Front Cover.

SMARTPHONE ATTACHMENT

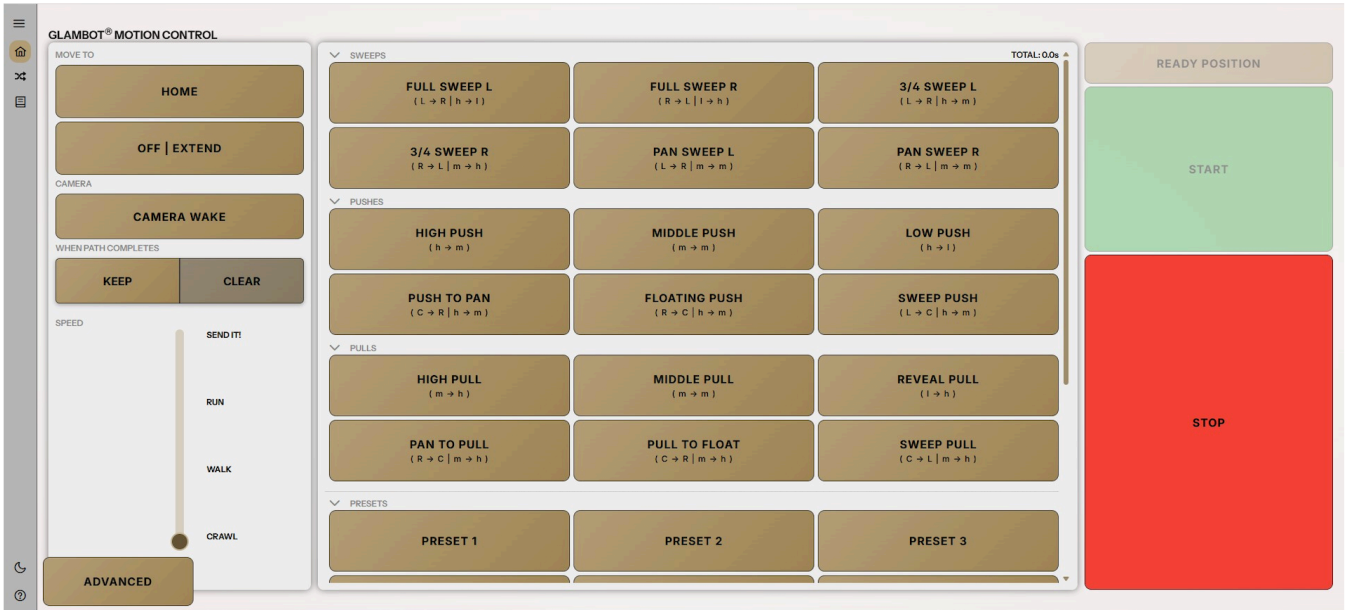
1. Align the universal bracket to the output bracket. The bracket is located using the (2) slots on the top edge. Install the (2) M5x16mm socket cap screws and flat washers using a 4mm hex key.



2. Install your phone into the universal bracket and secure by tightening the thumb screw clamp.

APPENDIX B: Glambot® Motion Control Details

Glambot® Motion Control is a custom control board for the robot that is accessible through the internet browser when the control device is linked to the local Glambot® Wi-Fi network.



MAIN SCREEN DEFINITIONS

Home: Moves to a collapsed position for stowing while the unit is powered.

OFF/Extended: Moves to a horizontal position used for powering off & assembling.

Paths: Controls the movement that will be executed to capture a video.

Sweeps: Paths that main movement is side-to-side.

Pushes: Paths that start away from the subject and move towards the target.

Pulls: Paths that start near the subject and move away from the target.

Presets: Unique saved path combinations.

Ready Position: Moves from current position to Start position of selected path then stops.

Start: Initiates movement after a path is selected.

Stop: Halts the robot at any point while executing a movement.

Camera Wake: Manually sends Bluetooth trigger to control device.

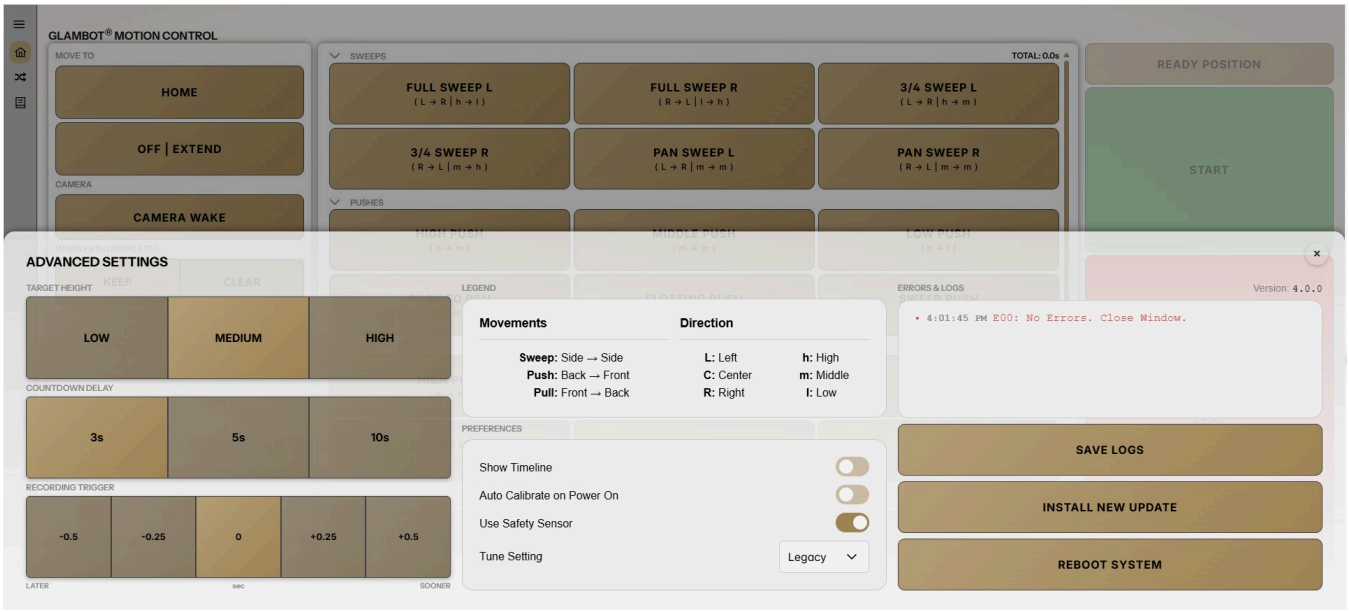
Keep | Clear: Sets if path remains selected or is unselected after being run.

Path Selection: Determines if the path selection is maintained or clears after execution.

Speed: Slider to select the overall speed of the robotic arm during a movement.

Time: Duration of the selected path(s).

Advanced: Additional tab to configure settings and view errors.



ADVANCED SCREEN DEFINITIONS

Target Height: Adjusts the focal height of the camera during the path.

Countdown Delay: # of seconds the motion pauses at the start pose prior to executing a path.

Recording Trig.: Coordinates the start of the Glambot® movement with start of recording.

Legend: Defines the abbreviations for the path directions + height at start and stop.

Show Timeline: Adds a timeline of the selected paths to the top of the Main Screen.

Auto Calibrate: Automatically begins calibration after assembling and powering on the unit.

Safety Sensor: Activates the safety sensor (sold separately) during operation.

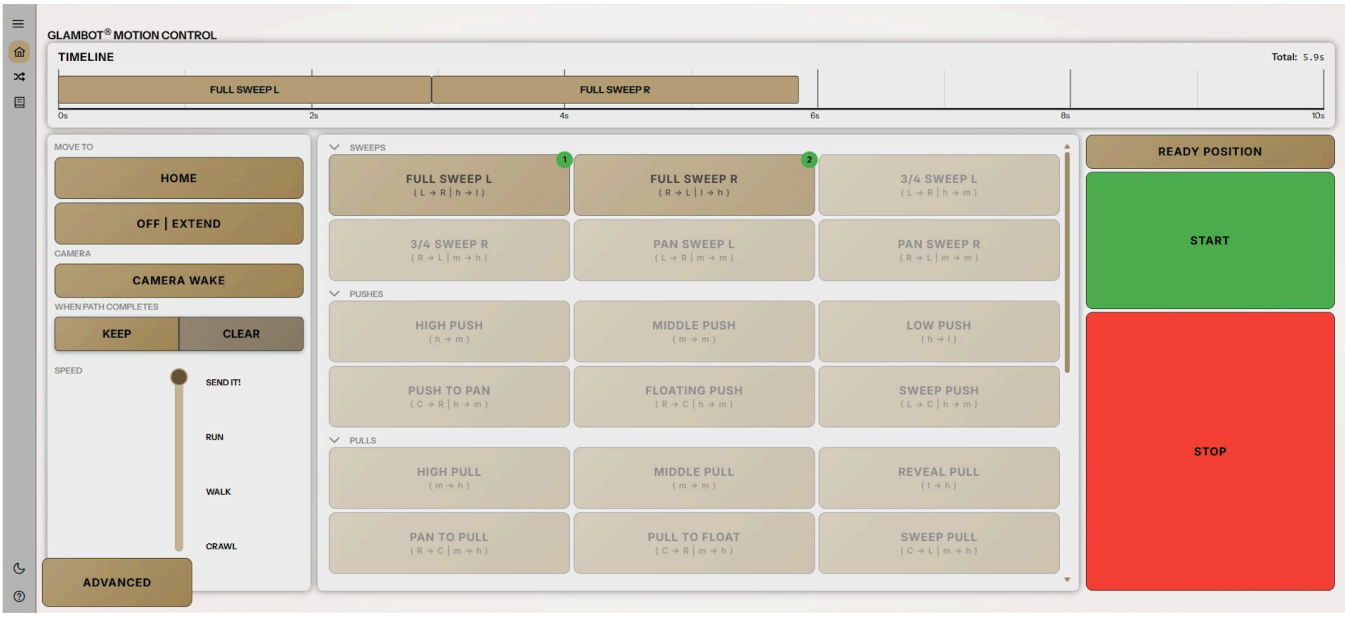
Tune Setting: Optional setting to fine tune motor performance.

Error Log: Shows error message for troubleshooting.

Save Logs: Downloads logs to the device for sharing with Glambot® technicians.

Update: Initiates an over-the-air software update.

Reboot System: Restarts the CPU + Glambot® Motion Control only.



IN-USE SCREEN DEFINITIONS

☰ Expands side bar menu

🏠 Home Page for Glambot Motion Control

🔀 Custom Path Designer application

📖 Library of custom paths

?: Initiates tutorial - only applicable in Custom Path Designer

❶,❷,... Bubbles indicate order of path execution.

Timeline: Optional setting to show the order and length of selected paths.

🌙 -or- ☼ Toggle between Light Mode and Dark Mode

APPENDIX C: Troubleshooting Guide

BEFORE YOUR START:

- Remember to first check that the E-STOP is ON and the power strip switch is ON.
- Refresh the Glambot® Motion Control with each restart to ensure the error code is updated and accurate - clear the cache if needed.
- If errors persist after complete troubleshooting, contact Glambot® support for advanced procedures: +1 (855) GLAMBOT.

E-CODE	ERROR MESSAGE	TROUBLESHOOTING STEPS
E11	Bluetooth Communication Error: Check USB connections to BLUETOOTH BOARD	BLUETOOTH BOARD is located in the BASE and connects to the back side of the CPU. 1. Remove the perforated magnetic cover on the right side of the unit,. 2. With the power on, confirm the RED LED on the BLUETOOTH BOARD is on. 3. If on, restart system. If not, check USB cable connection from BLUETOOTH BOARD to CPU. 4. If connection is OK and issue persists, try plugging into a different USB port on the CPU.
E12	Wrist Communication Error: Check USB connections to WRIST BOARD	WRIST BOARD is located inside the Tower on the lower left of the back wall. 1. Check that USB cable connection from the WRIST BOARD to CPU. Restart the system. 2. If the error persists, remove the front cover to check the USB connection at the WRIST BOARD. If connected a red LED on the board shall be lit. 3. If both connections are OK and issue persists, try plugging into a different USB port on the CPU.
E13	Wrist 1 Error: Check cable connections to WRIST 1 MOTOR	Wrist Board is located inside the Tower on the lower left of the back wall. 1. Check that assembly related cables are connected: • Cable 21 connection from Wrist Motor to Arm 2 connector panel. • Cable 19 connection to Arm 1 connector panel. • Cable 4/5 connection from power supply. • Cable 3 connection to power strip. • USB cable connection to CPU. 2. Restart the system. If error persists, continue to next step. 3. Remove the front cover to check connections to the Wrist Board. 4. Turn power on to the system to check status lights to inform next steps: A. If 2x red LEDs are on, check that the output cables are connected. If any connection is corrected at any point, restart the system. • Cable 19 connection to Arm Board • Jumper cable within board from clear USB hub to board mounted connectors. B. If only the upper right LED is on, check that micro USB cable connection to Wrist Board. If connected red LED on board shall be on. C. If only the lower right LED is on, check the power inputs to the Wrist Board. If either case is corrected the red LED on board shall be on. • Cable 18 power connection to Wrist Board. • Confirm the power switch on the Wrist Board is in the 'ON'
E13	Wrist 2 Error: Check cable connections to WRIST 2 MOTOR	1. Check the Cable 22 connections at the Wrist 1 motor and Wrist 2 motor. 2. Restart the system.

E13	Wrist 2 Error: Check cable connections to WRIST 2 MOTOR	1. Check the Cable 22 connections at the Wrist 1 motor and Wrist 2 motor. 2. Restart the system.
E13	Wrist 3 Error: Check cable connections to WRIST 3 MOTOR	1. Check the Cable 23 connections at the Wrist 2 motor and Wrist 3 motor. 2. Restart the system.
E14	Stepper Communication Error: Check USB connections to ARM BOARD	Arm Board is located inside the Tower on the lower left wall. 1. Check the USB Cable connection to CPU. If any connection is corrected at any point, restart the system. 2. Remove the front cover to check connections to the Arm Board. 3. Turn power on to the system and check the status lights to inform next steps: A. If all lights 3x Orange LEDs are on, check USB cable is connection to Arm Board. B. If NO lights are on, check Cable 15 is connected to Arm Board and 12V distribution board.
E15	Stepper Connection Error: Check cable connections to ARM BOARD.	ARM BOARD is located inside the Tower on the lower left wall. 1. Check that assembly related cables are connected: • Cable 8 and Cable 9 to Lift motor. • Cable 10 and Cable 12 to Arm 1 connector panel. • Cable 1 and Cable 2 connections to power strip. 2. Restart the system. If error persists, continue to next step. 3. With the power on, check status light on motors: A. If Lift motor and Elbow motor lights are Green, move to Step 6. B. If either motor light is off continue to next step. 4. Remove the front cover to check connections to internal components. 5. Turn power on to the system to check status lights to inform next steps: C. If Info light is Orange for any power supply, check the incoming power cable. • Lower right power supply, check Cable 1 connection for lower power supply. • Upper left power supply, check Cable 2 connection for upper power supply. D. If both power supply status lights are Green, move to next step. 6. With front cover removed, turn power on to the system to check connections to Arm Board: E. If only **3x Orange LEDs** are on, check connections to each motor. If connection is corrected, restart system. Otherwise move to next step. • Cable 11 and Cable 13 to Elbow motor. • Cable 6 and Cable 7 to Pan motor. F. If only **3x Orange LEDs** are on, check connections to power supplies. • Cable 6 and Cable 10 to the lower right power supply. • Cable 8 to the upper left power supply. G. If all **3x Orange LEDs** are on AND any neighboring Green LEDs are on, check connections to ARM BOARD. • If the first 3x Green LEDs are on, check Cable 7 connection to Arm Board. • If the middle 2x Green LEDs are on, check Cable 9 connection to Arm Board. • If the third Green LED is on, check Cable 13 connection to Arm Board.

E16	Stepper Setup Error: Check jumper setting on ARM BOARD	Arm Board is located inside the Tower on the lower left wall. 1. Remove the front cover to check the settings on the Arm Board. 2. Confirm the jumper is at location #3 and the 3x Orange LEDs are on. Restart system.
E17A	Motor Engagement Error: Support Arm 1 and restart system	Support Arm 1 and restart system.
E17B	Motor Engagement Error: Align Arm 2 vertically and restart system	Ensure Arm 1 is supported during initialization in conjunction with the steps below. 1. Orient Arm 2 vertically and restart system. • Note: even the slightest movement to vertical, or move away from vertical and back may be needed. 2. If persists, check Cable 16 connection to Lift motor brake. 3. Restart system.
E21	Wrist Runtime Error: Arrange arm to safe pose and restart system	Error signifies Wrist Motor wiring became disconnected during use. 1. Check LED status lights for each Wrist Motor. Note any flashing red lights. 2. Move arm to safe pose and restart system. Use 24V power supply to move Arm1 as needed. 3. Restart system and review start-up errors and follow start-up troubleshooting steps.
E22	[motor name] Motor Error: Arrange arm to safe pose and restart system err=0x(hex string), msg=(string)	Error signifies Arm Motor wiring became disconnected during use. 1. Note error code for potential consultation with Glambot® technician. 2. Check LED status lights for Lift and Elbow motors. Note any flashing red lights. 3. Move arm to safe pose and restart system. Use 24V power supply to move Arm1 as needed. 4. Restart system and review start-up errors and follow start-up troubleshooting steps.

APPENDIX D: Safety Sensor

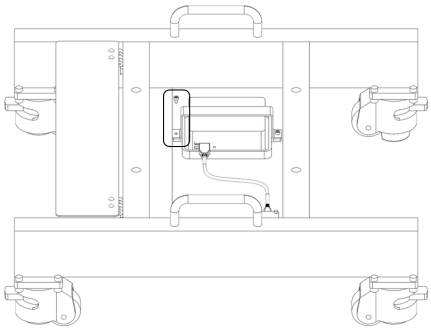
Glambot offers a Lidar based safety sensor (sold separately) to add a layer of protection over your activation. For use, refer to the following instructions for assembling the hardware and turning on the functionality. Please read each step thoroughly before completing it.

PARTS LIST:

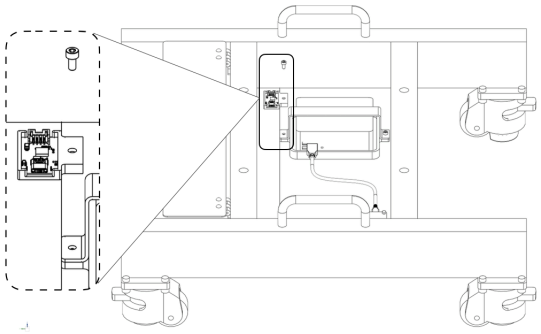
Part Name	Part No.	Qty
Sensor Assembly	613-00096	1
USB Cable	A-to-microB 0.5ft	099-40007	1
M4 x 10L Socket Cap Screw	452-00109	1

**Note: Recommended to perform this installation with the Glambot® disassembled.*

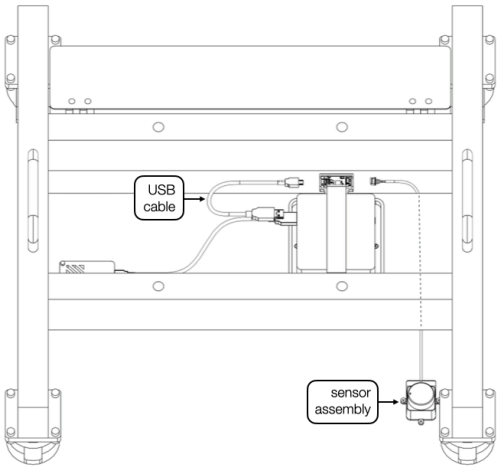
1. Remove the outer screw of the top bracket that secures the PC to the base. Then, ensure the existing USB cable to the rear of the PC is in the bottom port.



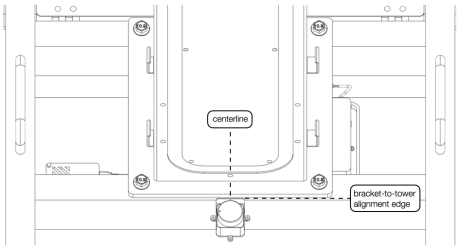
2. Install the board assembly at the bracket mounting hole location and secure with the longer M4 bolt provided.



3. Install the cables. Connect the USB cable between the Board and the top port of the PC. Set the sensor out front of the unit, route the cable under the base and connect to the Board.



4. With the Tower assembled, at the front of the base, align the notch in the Lidar mounting bracket with the center bolt of the LED light or cover panel. Locate the top edge of the bracket against the Tower and let the magnet hold the assembly in place.



5. Turn on the sensor feature within the Glambot Motion Control software by navigating to the Advanced Menu and selecting the 'Use Safety Sensor' toggle.

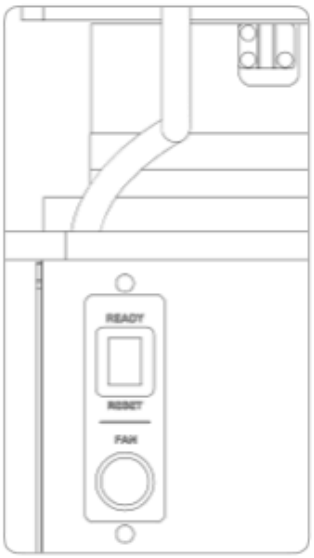
**Note: Glambot® Motion Control version 3.19.X or newer required to operate the sensor.*

APPENDIX E: Additional Features

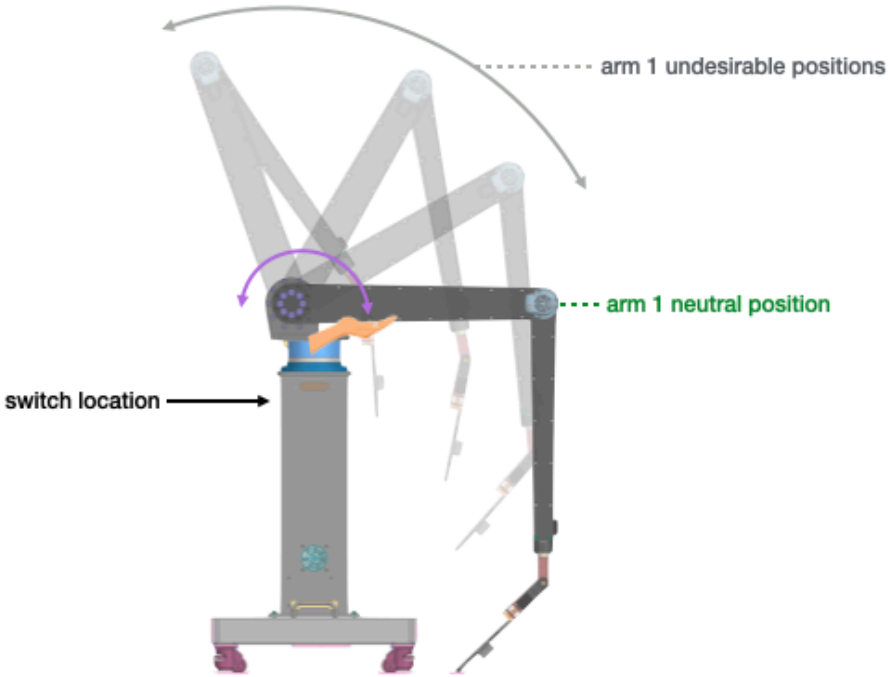
SHOULDER BRAKE:

The intended position for the Glambot® to be turned off in for assembly/disassembly is the 'OFF/ Extended" position (see Step 20). However, if power is lost when not in this position, there is an integrated tool that will allow manipulation of the arm back to the neutral position such that it may be restarted.

1. First, unplug the PC power brick from the power strip in the back of the BASE.
2. While supporting the arm, toggle the switch on the back of the tower from 'Ready' to 'Reset'. This will free the joint for movement and allow for movement to the neutral position.



switch detail



3. Once at the neutral position, toggle the switch back to the 'Ready' position.

   Note: the Glambot® will not operate with the switch in the 'Reset' position. The arm will fall to the ground and there is risk for damage if started with the switch in the 'Reset' position. Double check that the switch is in the 'Ready' position.

4. Re-plug the PC power brick and restart the system.

APPENDIX F: Recording Setup

Note: All the set ups assume using Snappic to record, edit, and share the video.

iPhone Filming

A. CONNECTING BLUETOOTH: Connect the iPhone on the wrist to the Glambot® Bluetooth. Ensure no other devices are connected to the Glambot® Bluetooth or it won't be discoverable.

B. CONNECTING SNAPPIC: Open the Snappic app of the iPhone. Next:

1. Open the event profile - Select Accessories - Volume Buttons - Done
2. Configure Camera - Back Ultra Wide Camera - Done
3. Start Photo Booth
4. Configure settings: Focus Smooth Focus - ON, Burst Focus Lock - OFF, Stabilization STANDARD
5. Start Photo Booth

WIRED Go-Pro Filming:

A. CREATING A WIRED CONNECTION:

1. Download the GoPro Quik app onto your Snappic iPhone, or other control device.
    a. drag down on the GoPro screen - Preferences - Connections - GoPro Quik app
2. On the Snappic device, open the GoPro Quik app
    a. bring both devices near each other - allow connection to both devices via Bluetooth
    b. to confirm successful connection, GoPro Quik app on iPhone should show GoPro battery percentage and/or show access to previous Glambot® video gallery
3. If not already done, attach the GoPro to the wrist end effector
4. Connect a 1.5-2ft USB-C cable to the Glambot® wrist-side USB-C "data" port Connect the other end of the cable to the GoPro.
5. Connect a 6ft USB-C cable to the Glambot® shoulder-side USB-C "data port Connect the other end of the cable to the Snappic device.
    a. to confirm successful connection, GoPro should appear with: "USB Connected" message

B. CONNECTING BLUETOOTH: Connect the iPhone on the wrist to the Glambot® Bluetooth. Ensure no other devices are connected to the Glambot® Bluetooth or it won't be discoverable.

C. CONNECTING SNAPPIC: Open the Snappic app of the iPhone.

1. Open the event profile - Select Accessories - Volume Buttons - Done
2. Configure Camera - GoPro Camera WIRED
3. Start Photo Booth

D. RECOMMENDED SETTINGS:

1. Drag down screen on GoPro and swipe right to show default settings
    a. Video Mode: Highest
    b. Controls: Pro
2. GoPro camera main screen should show default settings;
    a. 4X, L, Stabilization: on
    b. Standard: 1080/120/L
3. Open Snappic on iPhone, or other control device:
    a. Select "Video" and confirm settings are:
        i. Preset: Standard
        ii. Resolution: 1080
        iii. Frame Rate: 120fps
        iv. ISO Min & Mx: Auto
        v. Color Profile: Natural
        vi. Sharpness: Medium
        vii. Max Lens Mode: Off
        viii. Digital Lens: Linear/Max Super View
        ix. Anti-Flicker: 60Hz
        x. Bitrate: High
    b. Select "Slowmo" tab and confirm the settings are the same as above.

RESOURCES

Get a step-by-step video tutorial on setting up your Glambot®

If you have any questions during your deployment, please call +1 (855) GLAMBOT

For more information and videos visit: www.getglambot.com/glambot-resources

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